

# Addressing construct invalidity in partial interval recording data

---

James E. Pustejovsky

UT Austin

[pusto@austin.utexas.edu](mailto:pusto@austin.utexas.edu)

Thanks to collaborators:

Daniel Swan

Christopher Runyon

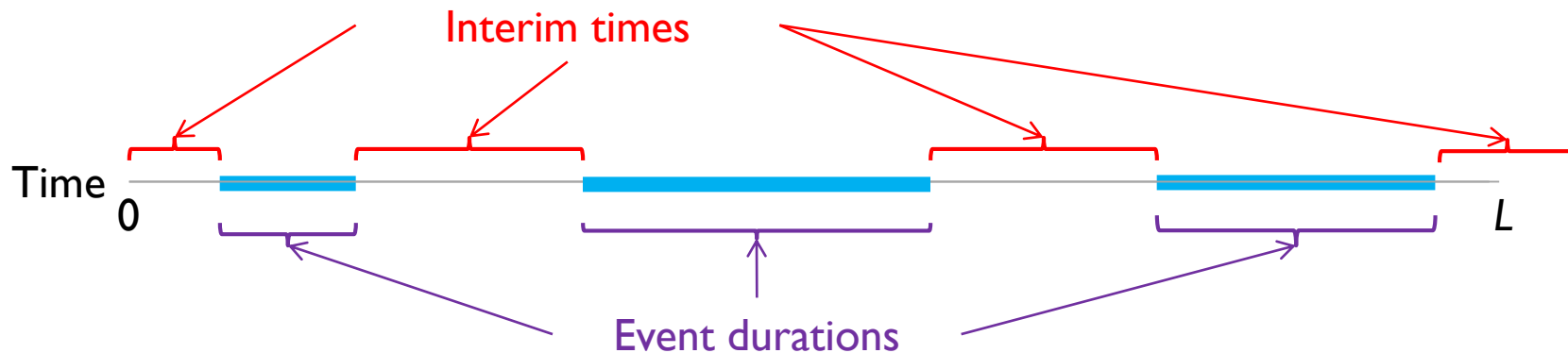
Texas Universities Education Statistics and Psychometrics Meeting

March 21, 2014

# Direct observation of behavior

- Applications in psychology and education research
  - Assessing teaching practice
  - Measuring student behavior
  - Evaluating interventions for individuals with disabilities

# The observed behavior stream

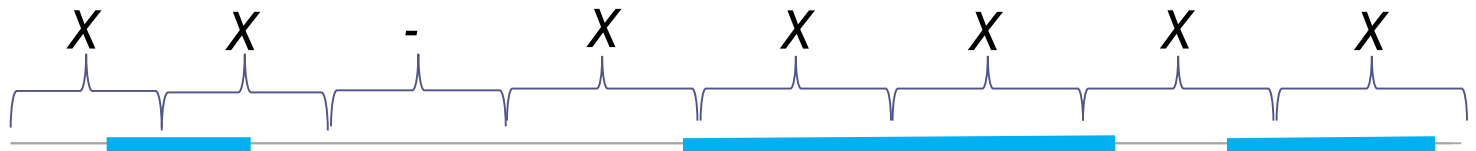


- Behavioral characteristics of interest
  - **Prevalence**: proportion of time that a behavior occurs
  - **Incidence**: rate at which new behaviors begin

# Partial interval recording (PIR)

- Divide observation time into  $K$  intervals, each of length  $c$ .
- For each interval, record whether behavior occurred **at any point** during the interval.
- Calculate the proportion of intervals with behavior:

$$Y^{PIR} = (\# \text{ Intervals with behavior}) / K.$$



# A model for observed behavior

## Equilibrium Alternating Renewal Process (Rogosa & Ghandour, 1991)

1. Event durations are identically distributed random variables, with mean duration  $\mu > 0$ .
2. Interim times (ITs) are identically distributed random variables, with mean IT  $\lambda > 0$ .
3. Event durations and ITs are all mutually independent.
4. Process is aperiodic and in equilibrium.

---

### Target parameters

• Prevalence (phi):  $\phi = \frac{\mu}{\mu + \lambda}$

Incidence (zeta):  $\zeta = \frac{1}{\mu + \lambda}$

# Construct invalidity of PIR

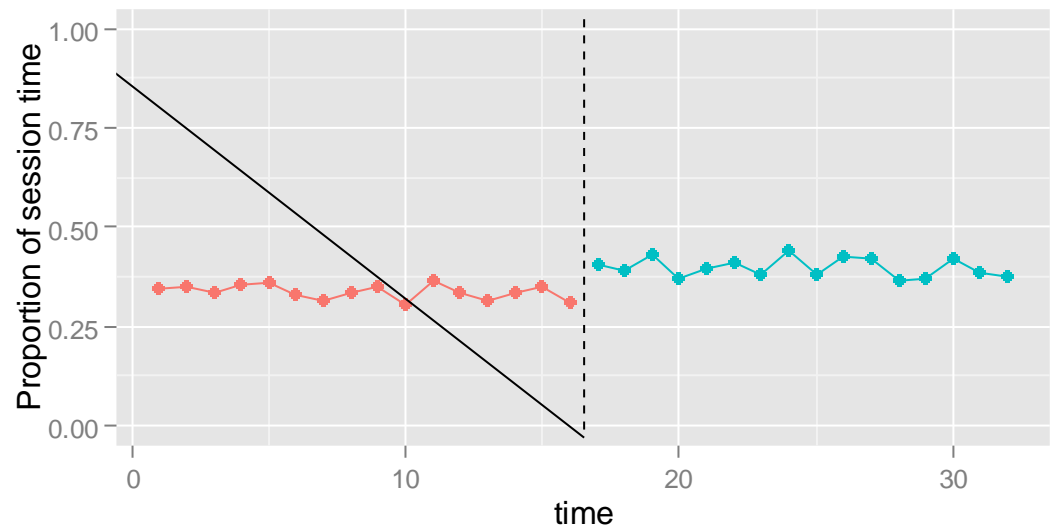
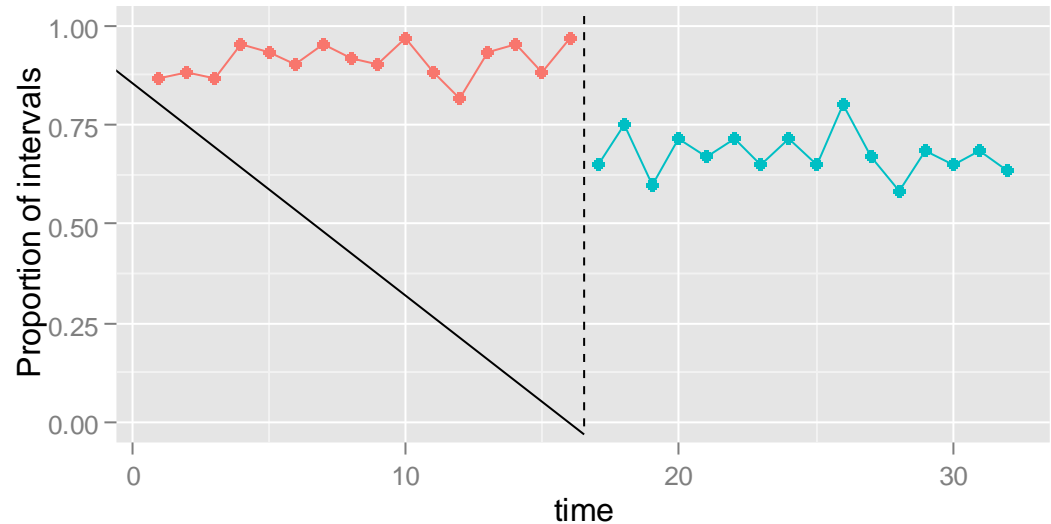
- Under an equilibrium alternating renewal process,

$$E(Y^{PIR}) = \phi + \zeta \int_0^c \Pr(IT > x) dx$$

# Potential for misleading inferences

Using PIR, it appears that prevalence decreases...

...when sample prevalence has instead increased slightly.



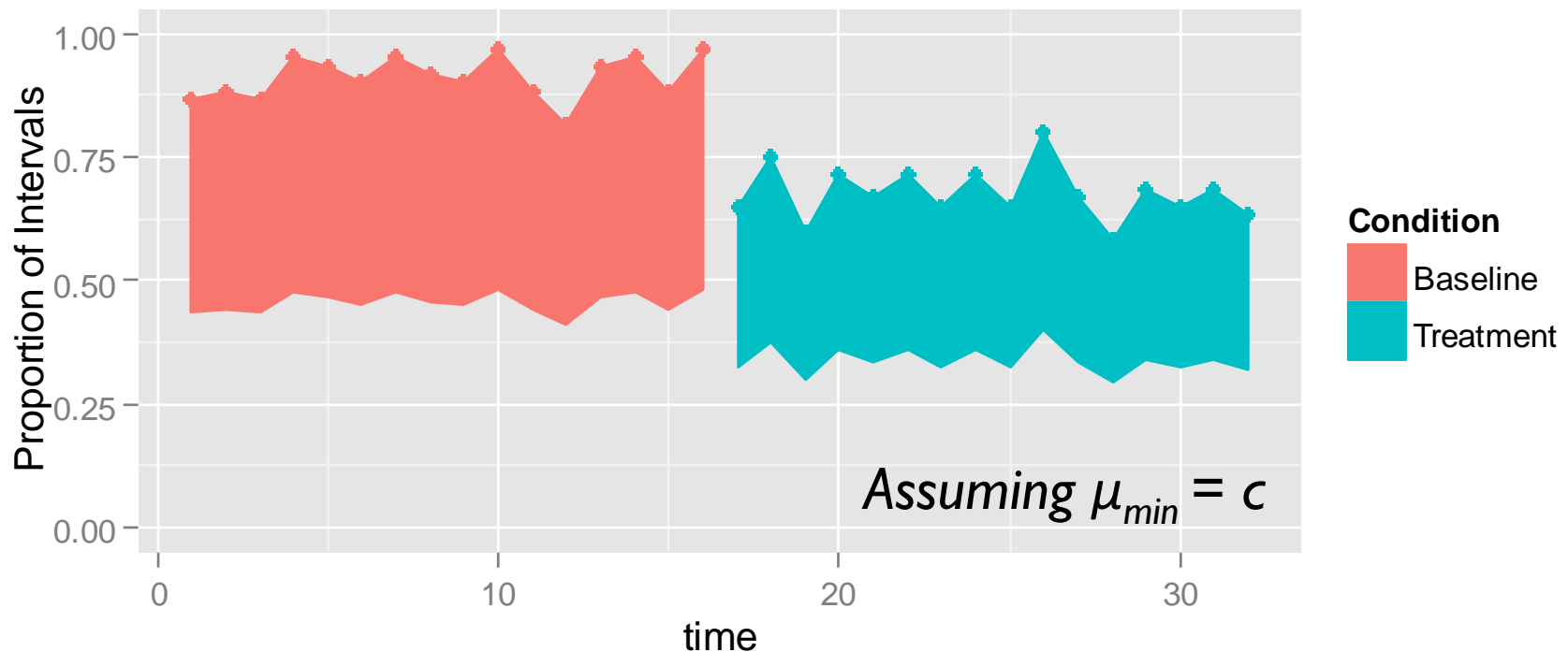
# Methods to address construct invalidity

1. If mean event duration is long
  - bound for prevalence
2. If mean event duration is short, interim times are mostly long
  - bound for incidence
3. If event durations and interim times are exponential
  - moment estimators for prevalence and incidence
4. If you can get interval-level data
  - Likelihood estimators for prevalence and incidence



# Method 1: A bound for prevalence

- Pick a value  $\mu_{min}$  where you are certain that  $\mu > \mu_{min}$
- It follows that 
$$\frac{\mu_{min}}{\mu_{min} + c} E(Y^{PIR}) < \phi < E(Y^{PIR})$$



# Discussion

- Methods all involve fairly strong assumptions
- Prospectively, choose interval length based on what you know about the behavior.
- Use partial interval recording only if one of the analytic methods can be justified a priori.

## Method 2: A bound for incidence

- Pick a value  $\mu_{max}$  where you are certain that  $\mu < \mu_{max}$
- Pick a value  $p$  where you are certain that  $\Pr(IT > c) > p$ .
- It follows that

$$\frac{E(Y^{PIR})}{\mu_{max} + c} < \phi < \frac{E(Y^{PIR})}{(1-p)c}$$

## Method 3: A bound for interim time ratio

- Two samples of PIR data,  $s = 0, 1$ , generated from  $ARP(\mu_s, \lambda_s)$ .
- Assume that  $\mu_0 = \mu_1$ .
- Assume that interim times are exponentially distributed.
- If  $E(Y_0) < E(Y_1)$ , then

$$\text{cll}[E(Y_1)] - \text{cll}[E(Y_0)] < \ln\left(\frac{\lambda_0}{\lambda_1}\right) < \text{logit}[E(Y_1)] - \text{logit}[E(Y_0)]$$

$$\text{cll}(x) = \ln(-\ln(1-x))$$

$$\text{logit}(x) = \ln(x) - \ln(1-x)$$

## Method 4: Moment estimators

- Assume that event durations and interim times are both exponentially distributed (i.e., Alternating Poisson Process).

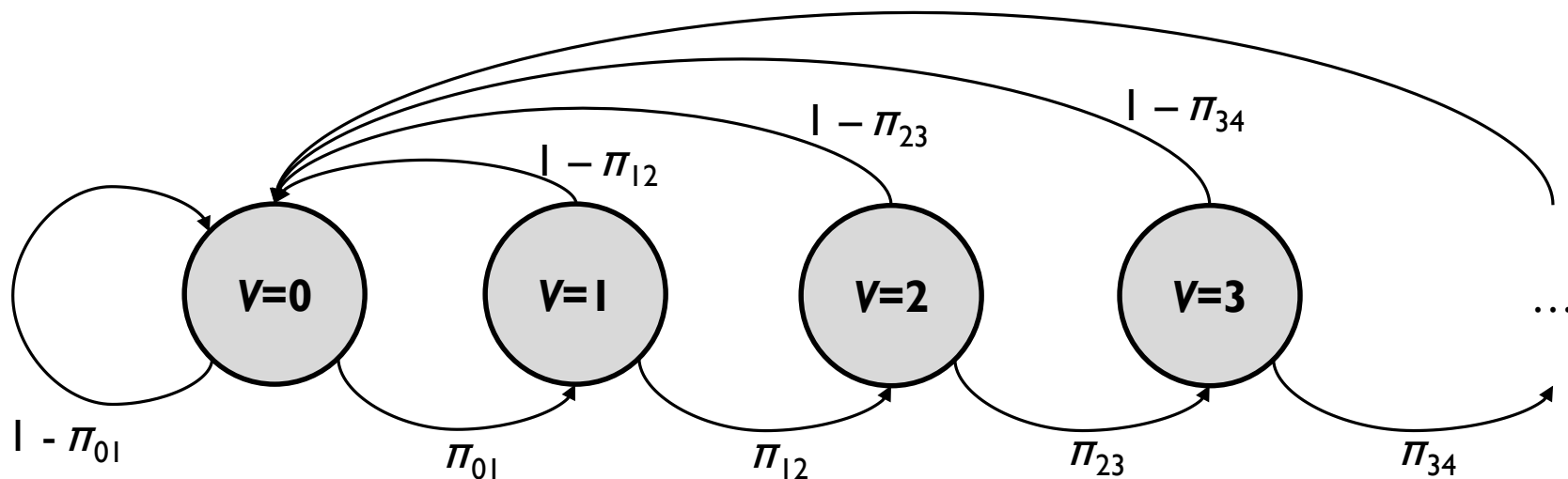
$$E(Y) = 1 - (1 - \phi) \exp\left(\frac{-\zeta c}{(1 - \phi)}\right)$$

$$Var(Y) = \frac{E(Y)[1 - E(Y)]}{K} \left[ 1 + \frac{2\phi}{KE(Y)} \sum_{k=1}^{K-1} (K - k) \exp\left(\frac{\zeta c}{\phi} - \frac{\zeta kL}{\phi(1 - \phi)K}\right) \right]$$

- Replace expectation and variance with sample mean and sample variance, solve for  $\phi$  and  $\zeta$ .
- Bootstrap confidence intervals.

# Method 5: Likelihood estimators with interval-level data

- Define  $V_k$  as the number of consecutive intervals where behavior is present,  $k = 1, \dots, K$ .
- Under the Alternating Poisson Process,  $V_1, \dots, V_K$  follow a Discrete Time Markov Chain on the space  $\{0, 1, 2, 3, \dots\}$ .



# DTMC model for PIR intervals

Transition probabilities:

$$\pi_{j,j+1} = \Pr(V_k = j+1 | V_{k-1} = j) = 1 - e^{-L/\lambda} \left[ 1 - f^{(j)}(0) \right]$$

where

$$f(q) = \frac{\phi - (\phi - q) \exp\left[\frac{-L\zeta}{\phi(1-\phi)}\right]}{1 - (1-q) \exp\left[\frac{-L\zeta}{(1-\phi)}\right]}$$

and  $f^{(j)}$  is the  $j$ -fold recursion of  $f$ .